ViewRec3D: Learning to Recommend 3D Viewpoints for AI Photography

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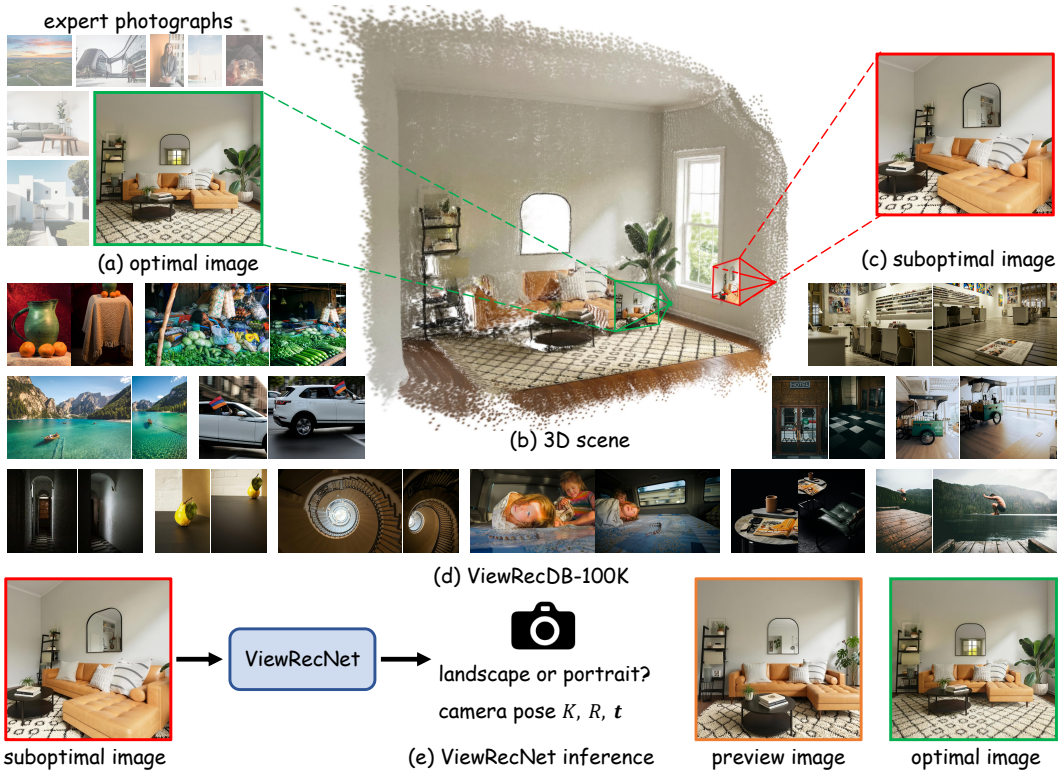


Figure 1: Treating an expert-selected photo as the optimal viewpoint (a), we first outpaint the image and reconstruct the 3D scene (b), and then render random alternative viewpoints and select high-quality results as the suboptimal image (c). In this manner, we build data pairs for viewpoint recommendation in AI photography, and curate the ViewRecDB-100K dataset (d). Using this dataset, we train a view recommendation model called ViewRecNet. Given an image as input, ViewRecNet predicts the expert viewpoint (e), which mimics that of the optimal image.

Abstract

Viewpoint dictates the photo composition and plays a vital role in AI photography. Existing 3D viewpoint recommendation methods are often *limited* in viewpoint adjustments, which is mainly due to their lack of high-quality training data with *accurate and large* 3D view changes. Ideally, the training data should contain suboptimal images and expert-selected optimal viewpoints, but this can be very expensive to curate. To solve this, we build an automatically-generated 3D viewpoint recommendation dataset from expert photos. Specifically, we first consider these

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expert photos as optimal and outpaint them to provide more information on scene layouts. Next, we explicitly reconstruct the 3D scene. We then render suboptimal images from random viewpoints. Lastly, we introduce a hierarchical data filtering scheme and acquire high-quality data pairs for our ViewRecDB-100K dataset. On top of this, we further introduce a view recommendation model, ViewRecNet, that can predict expert viewpoints from any suboptimal image inputs using a ray-based dense supervision. The proposed method achieves strong results both quantitatively and qualitatively, supported by LLM-based viewpoint preference and human studies. Data and code are available at link.

1 Introduction

Camera viewpoints play a major part in determining photography composition, which involves arranging visual elements within the frame to create a compelling, organized image that guides the viewer's eye [11]. Since photography composition can significantly affect the overall visual appeal, for an AI photographer that aims to help users capture better photographs, viewpoint recommendation becomes an essential component with significant practical value.

Despite the practical importance of viewpoint recommendation in AI photography, existing methods still struggle to propose high-quality 3D viewpoints. In fact, these proposed viewpoints are often under limited changes when compared to the original suboptimal viewpoint, *e.g.*, very small or no significant translation and rotation changes [9, 28]. We believe that this limitation is mainly due to the lack of high-quality training data with large and accurate viewpoint changes.

In this work, we introduce a 3D viewpoint recommendation dataset, ViewRecDB-100K, that includes suboptimal images and expert-selected 3D viewpoints, as illustrated in Fig. 1. To avoid the high cost of manually curating such data from scratch, we introduce an automatic data generation method. We consider the expert-selected best-looking photographs from the Unsplash dataset [17] as optimal images following [6, 28], and render suboptimal images from random viewpoints. Specifically, we adopt a 3D-reconstruction-based approach when rendering the suboptimal images. First, we outpaint the optimal image to expand the scene with possible layouts. Next, we reconstruct the expanded image in 3D Gaussian splats (3DGS) [7]. We then randomly select alternative viewpoints for image rendering and adopt an open-source model [4] for perspective restoration and hole filling. Lastly, we introduce a hierarchical filtering pipeline that progressively filters out low-quality outputs across all stages, including image outpaints, 3D viewpoints, renders, and final restored images. With the help of a 3D expert model DA3 [10] and an LLM [16], the filtering pipeline collects high-quality data pairs with a wide range of viewpoint changes. Overall, we curate 104,704 data samples from diverse scenarios and construct the ViewRecDB-100K dataset.

On top of the dataset, we introduce a viewpoint recommendation model, termed ViewRecNet. Given an input image, ViewRecNet predicts an expert viewpoint represented by the view orientation and camera pose (intrinsics and extrinsics). Additionally, we convert camera pose changes from suboptimal images to optimal images as relative changes in terms of rays, and leverage a ray-based dense supervision [31]. Paired with the similar novel view synthesis approach used in dataset generation, the recommended viewpoints can be rendered as image previews (see Fig. 1).

Lastly, for evaluation, we build the ViewRecEval benchmark using 1,000 professionally verified data samples. We also introduce an LLM-based viewpoint preference rater that uses chain-of-thought (CoT) reasoning. Experimental results on this benchmark demonstrate that ViewRecNet achieves strong performance both quantitatively and qualitatively.

2 Related Work

Photography Composition Optimization. Photography composition optimization aims to improve subject placement, scale, and spatial relationships with other visual elements. Existing methods primarily achieve this through 2D cropping. FCDB [1] provides human-annotated cropping windows and pairwise preferences, CPC [23] ranks candidate views, GAICD [30] assigns quality scores to grid-based candidate crops, and SACD [27] provides subject-aware cropping annotations and rankings. Other methods learn compositional preferences from professional photographs [2], or

Table 1: Viewpoint recommendation dataset comparison. #Scenes indicates the number of collected photographs that are considered optimal. #Images denotes the total number of candidate viewpoints.

Dataset	2D/3D	Generation method	#Scenes	#Images	Open Source
FCDB [1]	2D	Expert Annotation	1,743	34,130	✓
CPC [23]	2D	Expert Annotation	10,800	259,200	✓
GAICD [30]	2D	Expert Annotation	1,236	106,296	✓
SACD [27]	2D	Expert Annotation	2,777	more than 24,000	✓
PPC [28]	3D	Video-based Generation	5,000	5,000	✗
PCARD [9]	3D	Panorama Sampling	4,000	324,000	✗
ViewRecDB-100K (Ours)	3D	3D Reconstruction	76,010	104,704	✓

construct training pairs by outpainting professional photographs, as in GenCrop [6]. Regarding model design, CACNet [5] incorporates composition patterns to guide cropping, while Venus [3] leverages multimodal large language models to provide interpretable aesthetic guidance and cropping results. However, 2D cropping is constrained by the original viewpoint and cannot alter perspective and occlusion relationships through camera movement.

Geometry-Aware Image Synthesis. Feed-forward geometry models [22, 18, 10] have made significant progress in recovering 3D structure and camera parameters from images. For single-image inputs, MoGe [21] estimates dense geometry for open-domain images, while SHARP [13] predicts 3D Gaussian representations for efficient novel view synthesis. Such explicit 3D representations support controllable rendering under specified camera transformations. Meanwhile, image editing models [25, 8, 12, 20, 26] demonstrate strong capabilities in object addition and removal, attribute modification, background replacement, and style transfer, producing high-quality, photorealistic images while preserving content unrelated to the intended edits. These advances support our data generation pipeline, which combines geometry-based novel view rendering for controllable viewpoint changes with generative refinement to complete missing regions and reduce rendering artifacts.

Viewpoint Recommendation. 3D viewpoint recommendation improves photography composition by adjusting camera position, rotation, and field of view. The types and ranges of viewpoint changes represented in the training data determine the adjustments a model can learn. SPAS [9] constructs PCARD by sampling views with different orientations from panoramic images. Since these views share the same camera center, the resulting training pairs contain no translation changes. PPC [28] uses ViewCrafter [29] to generate viewpoint transformation data from expert photos and trains a video generation model for viewpoint recommendation. However, its data generation process restricts rotation to a relatively small range to maintain visual quality and content consistency. In contrast, our 3D-reconstruction-based pipeline constructs training pairs that cover rotation, translation, FoV changes, and landscape/portrait orientation changes, while preserving valid samples with large viewpoint variations. The resulting dataset therefore covers more types of viewpoint changes and a wider range of adjustments, enabling more flexible viewpoint recommendation.

3 The ViewRecDB-100K Dataset

3.1 Data Generation

Our large-scale 3D viewpoint recommendation dataset, ViewRecDB-100K, contains 76,010 optimal images and 104,704 suboptimal images. Following [6, 28], optimal images are collected from the Unsplash dataset [17], which contains 6.5M high-quality photographs. We only consider "featured" photographs, which include roughly 300k editor-selected high-quality images. We then generate the suboptimal images and the corresponding viewpoint changes (see Fig. 2). Each optimal image defines a unique scene and is associated with one or two suboptimal images. Compared with existing viewpoint recommendation datasets, ViewRecDB-100K contains the largest number of scenes, demonstrating its diversity (Tab. 1).

As shown in Fig. 2, given the optimal image I, we aim to generate a suboptimal image $\tilde{I}$ from a novel viewpoint via outpainting, 3D reconstruction, novel view rendering, and lastly image restoration. We record the viewpoint change from suboptimal image $\tilde{I}$ to optimal image I as,

$$\boldsymbol{v} = (\boldsymbol{s}, \boldsymbol{q}, \boldsymbol{t}), \tag{1}$$

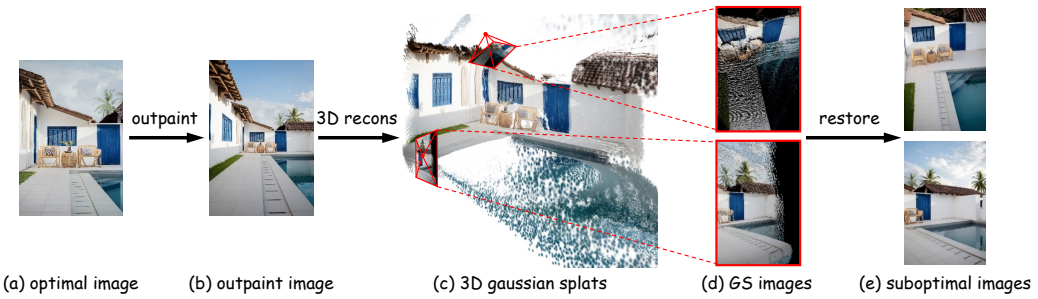


Figure 2: **Data generation method.** Given an optimal image (a), we first determine whether orientation adjustment is required and outpaint the image (b). We then reconstruct the complete 3D scene (c) and render multiple Gaussian splatting (GS) images (d) from random viewpoints. Finally, we restore holes or other artifacts in GS images to get corresponding suboptimal images.

where $\boldsymbol{s} \in \mathbb{R}^2$ denotes FoV change ratio from $\tilde{I}$ to I, and $\boldsymbol{q} \in \mathbb{R}^4$ and $\boldsymbol{t} \in \mathbb{R}^3$ denote rotation quaternion and translation vector from $\tilde{I}$ to I, respectively.

Outpainting. We use Qwen-Image-Edit [25] to outpaint I to provide a possible estimate of the scene. This step enlarges the viewpoint while keeping the optimal view centered. As a result, subsequent viewpoint changes are more likely to preserve a large portion of the content in the optimal view, making the later restoration of the optimal viewpoint rely more on visible evidence instead of model priors. The entire outpainting module can be formulated as,

$$I_{\text{outpaint}} = \mathcal{F}_{\text{outpaint}}\left(I, o, \boldsymbol{s}^{-1}\right), \tag{2}$$

where $o \in \{0, 1\}$ denotes the binary orientation-change decision, and $\boldsymbol{s} \in \mathbb{R}^2$ denotes the field-of-view (FoV) change ratio from I_{outpaint} to I. We feed the inverse of the FoV change ratio $\boldsymbol{s}^{-1}$ since the operation $\mathcal{F}_{\text{outpaint}}(\cdot)$ is on I, not the other way around.

3D reconstruction and novel view rendering. We first feed I_{outpaint} into SHARP [13] to obtain 3D Gaussian splats of the scene $\mathcal{G} = \mathcal{F}_{\text{recons}}(I_{\text{outpaint}})$. We then sample a random view i and render the corresponding Gaussian splatting (GS) image I_{gs} from the reconstructed 3D scene $\mathcal{G}$. This can be formulated as follows,

$$I_{\text{gs}} = \mathcal{F}_{\text{render}}\left(\mathcal{G}, R^\top, -R^\top \boldsymbol{t}\right), \tag{3}$$

where $R \in \mathbb{R}^{3\times3}, \boldsymbol{t} \in \mathbb{R}^3$ denote the rotation and translation from GS image I_{gs} to optimal image I[1]. Again, inverse rotation $R^\top$ and inverse translation $-R^\top \boldsymbol{t}$ are fed into $\mathcal{F}_{\text{render}}(\cdot)$ since the operation is on Gaussian splats from I, not that from I_{gs}.

Image restoration. We use Qwen-Image-Edit [25] with a LoRA specialized for Gaussian-splatting restoration [4]. Specifically, the restoration model takes I_{gs} together with the outpainted image I_{outpaint} as input:

$$\tilde{I} = \mathcal{F}_{\text{restore}}\left(I_{\text{gs}}, I_{\text{outpaint}}\right), \tag{4}$$

where $\tilde{I}$ denotes the restored suboptimal image. This process removes holes and rendering artifacts in I_{gs} while preserving the viewpoint and scene content of the GS rendering.

Hierarchical filtering. As shown in Fig. 3, we adopt a three-stage hierarchical filtering scheme.

First, for outpainted image I_{outpaint}, we crop out the region from I_{outpaint} that corresponds to I and compare their similarity to verify their consistency.

Second, for Gaussian splat render I_{GS}, we use a LLM [16] to filter them according to three criteria: subject consistency and completeness, ease of restoration, and depth consistency.

Third, for the suboptimal image $\tilde{I}$, we estimate the relative camera pose between I and $\tilde{I}$ using VGGT [18], and filter samples based on the Relative Rotation Accuracy (RRA) and Relative Translation Accuracy (RTA) with the 3D render ground truth. Moreover, we use an LLM to further validate: (1) no visible artifacts, distortions, or noise in $\tilde{I}$; (2) no subject changes compared with I_{outpaint}; and (3) pixel-level positional consistency with I_{gs}.

[1]The rotation matrix R in Eq. 3 is equivalent to the rotation quaternion $\boldsymbol{q}$ in Eq. 1.

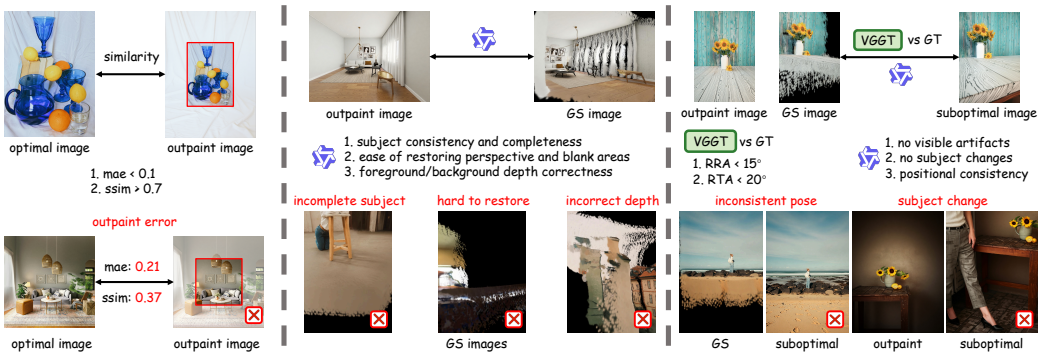


Figure 3: **Hierarchical filtering** for outpainting, novel views, and image restoration (left to right).

LLM Preference Rater Prompt

[Task]
You are a professional expert in photographic composition analysis. Your task is to compare two photos taken from different viewpoints (img1, img2) strictly based on photographic composition, and determine which photo has the better composition.

[Rule]
1. Identify the subject in img1 and img2 ...
2. Determine the genre and mode of expression of img1 and img2 ...
3. For each image, determine if the subject is clear, prominent, reasonably positioned, appropriately scaled, well coordinated with the background …
4. Explain the comparison process …

[Example]
{"input": img1, img2, "reasoning": "...", "preference": "..."}, …

Figure 4: Text prompt for LLM rater.

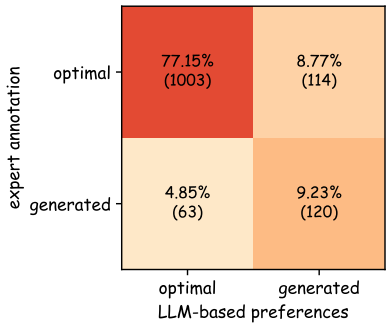


Figure 5: Confusion matrix between professional photographer preferences and LLM preferences.

Discussion. Our pipeline is not restricted to a specific input format and can synthesize images from an arbitrary number of candidate viewpoints. This makes the dataset highly scalable: with sufficient computational resources, its scale can be continuously expanded. Moreover, as 3D reconstruction techniques continue to advance, or when multi-view reconstruction methods are adopted, the quality of the generated data is expected to further improve.

3.2 Benchmark

For performance evaluation of 3D viewpoint recommendation, we construct a dedicated benchmark called ViewRecEval. Specifically, from a total of 1,300 expert-annotated preference pairs, we select 1,000 sample pairs, in which I is confirmed to exhibit superior photography composition than $\tilde{I}$.

LLM-based viewpoint rater.

Since photographic composition quality is difficult to quantify precisely, we formulate its evaluation as a pairwise comparison problem and introduce an LLM-based viewpoint rater with a CoT prompt to compare two images under professional photographic criteria. The prompt is refined based on professional photographer feedback and 100 annotated preference pairs with explanations. As shown in Fig. 4, the prompt guides the LLM through a step-by-step process in determining the viewpoint and photography composition preference.

When validated on 1,300 expert-annotated samples, the LLM judgment achieves an overall agreement of 86.38% with the expert annotations, indicating that the LLM-based viewpoint rater aligns well with human preferences.

4 The View Recommendation Model

Given a suboptimal image $\tilde{I}$, the view recommendation model $f(\cdot)$ predicts,

$$(\hat{o}, \hat{\boldsymbol{v}}) = f(\tilde{I}), \tag{5}$$

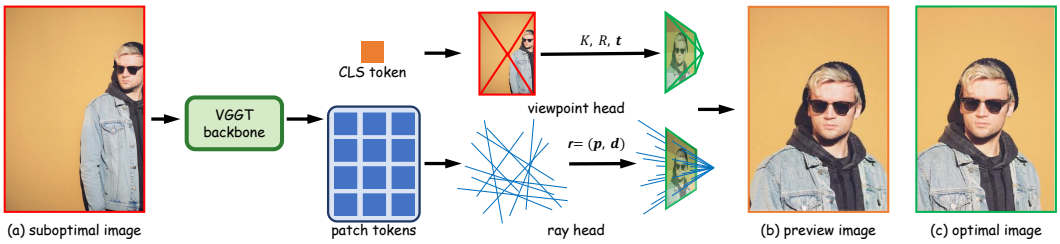


Figure 6: **ViewRecNet architecture.** Given a suboptimal image (a) as input, we use the VGGT backbone to generate the CLS token and patch tokens. The viewpoint head predicts the expert viewpoint based on the CLS token, while the ray head takes patch tokens as input and predicts camera rays for each patch. The predicted viewpoint can be used to generate the corresponding preview image (b), which is expected to mimic the optimal image (c).

where $\hat{o} \in \{0, 1\}$ is a binary orientation change indicator, and $\hat{\boldsymbol{v}} = (\hat{\boldsymbol{s}}, \hat{\boldsymbol{q}}, \hat{\boldsymbol{t}})$ represents the predicted viewpoint change from $\tilde{I}$ to the optimal image I, including $\hat{\boldsymbol{s}} \in \mathbb{R}^2$ to estimate the FoV change, and $\hat{\boldsymbol{q}} \in \mathbb{R}^4$ and $\hat{\boldsymbol{t}} \in \mathbb{R}^3$ to denote the estimated camera pose change.

Patch-as-ray representation. Since camera pose supervision for the recommended viewpoint $\boldsymbol{v}$ is sparse, we introduce a dense geometric supervision following the cameras-as-rays paradigm [31]. Specifically, across all N_{patch} patches, each patch $i \in \{1, ..., N_{\text{patch}}\}$ corresponds to a ray,

$$\boldsymbol{r}_i = (\boldsymbol{p}_i, \boldsymbol{d}_i), \tag{6}$$

where $\boldsymbol{r}_i \in \mathbb{R}^6$ represents the camera ray passing through the center of the i-th patch, while $\boldsymbol{p}_i \in \mathbb{R}^3$ and $\boldsymbol{d}_i \in \mathbb{R}^3$ denote the origin and direction of the i-th ray, respectively.

The ray origin is set to the camera center for the optimal image I, which is given by $\boldsymbol{t}$. We denote the homogeneous center pixel coordinate of the image region corresponding to the i-th patch as $\boldsymbol{c}_i = (u_i, v_i, 1)^\top$. By back-projecting $\boldsymbol{c}_i$ into the world coordinate system, we obtain the ray direction:

$$\boldsymbol{d}_i = \frac{RK^{-1}\boldsymbol{c}_i}{\|RK^{-1}\boldsymbol{c}_i\|_2}, \tag{7}$$

where R denotes the rotation matrix from the suboptimal image $\tilde{I}$ to the optimal image I, and K denotes the camera intrinsic matrix. Since the camera intrinsics of the expert-suggested viewpoint are unavailable, we assume a fixed FoV for all input suboptimal images and use $\boldsymbol{s}$ to derive the FoV and intrinsic matrix K of the optimal viewpoint. In this way, patch-as-ray supervision provides dense constraints on both the camera intrinsic and extrinsic parameters.

4.1 Model Architecture

Our model consists of three main components: a VGGT backbone, a camera head for viewpoint recommendation, and a patch head for ray-based dense supervision.

VGGT backbone. We adopt pretrained VGGT [18] as a feature backbone, and use its camera token (CLS token) and patch tokens for subsequent prediction.

Camera head. Taking the CLS token as input, we use a two-layer MLP classifier to predict o, and adopt the same VGGT [18] camera head to predict $\boldsymbol{v}$.

Patch head. The camera ray map is predicted from the patch tokens using a three-layer MLP. Specifically, the MLP is shared across all patches and predicts $\boldsymbol{r_i}$ for the i-th patch token separately.

4.2 Training Objective

We train ViewRecNet end-to-end using a multi-task loss:

$$L = L_{\text{orientation}} + \alpha L_{\text{view}} + L_{\text{rays}}, \tag{8}$$

where $L_{\text{orientation}}$ adopts binary cross-entropy to supervise the landscape or portrait decision, L_{view} adopts Huber loss on the 9-dimensional view descriptor $\boldsymbol{v}$ in Eq. 1 following [18], and L_{rays} is a $\mathcal{L}_2$ reconstruction loss over the 6-dimensional ray representation $\boldsymbol{r}_i$ (see Eq. 6) for each patch token i. We set $\alpha = 10$ by default. See Section B.1 for the sensitivity analysis.

Table 2: Quantitative comparison. AUC@30 is the area under the accuracy-threshold curve up to 30°, computed based on RRA. GPT-Pref measures the pairwise preference between each baseline and our method. GPT-Imp measures whether the generated image is preferred over the input suboptimal image. Human-Pref reports the percentage of samples for which each method is selected as the best among our method and all baselines. Ref denotes the reference data used in GPT pairwise comparisons.

Method	Image-level Consistency				Pose-level Consistency		Preference		
	SSIM↑	LPIPS↓	PSNR↑	CLIP-I↑	AUC@30↑	Dist.↓	GPT-Pref.↑	GPT-Imp.↑[2]	Human-Pref.↑
CACNet	0.3616	0.7178	14.89	0.8608	0.3157	0.4843	34.40%	–	20.50%
Venus-Q	0.3584	0.7330	14.73	0.8623	0.2990	0.4475	25.60%	–	20.20%
PPC	0.3915	0.7167	15.10	0.6977	0.3060	0.5961	32.10%	53.10%	4.22%
SPAS	0.3751	0.7120	15.05	0.8421	0.4686	0.4587	35.70%	52.00%	10.60%
ViewRecNet	**0.3929**	**0.6919**	**15.31**	**0.8812**	**0.5271**	**0.3080**	Ref.	**67.80%**	**44.48%**

4.3 Preview Image Rendering

To provide visual previews of the predicted viewpoint $\hat{\boldsymbol{v}}$, we take a similar pipeline to that used in Section 3.1. Specifically, given the suboptimal image $\tilde{I}$, we first 3D reconstruct the 3D scene $\hat{\mathcal{G}}$ using $\mathcal{F}_{\text{recons}}(\cdot)$, then render the proposed view $\hat{I}_{\text{render}}$ (with the predicted $\hat{R}$ and $\hat{\boldsymbol{t}}$, not their inverse) using $\mathcal{F}_{\text{render}}(\cdot)$, and lastly restore the image $\hat{I}$ using $\mathcal{F}_{\text{restore}}(\cdot)$. No filtering is included.

5 Experiments

5.1 Experimental Setup

Training details. Selecting 100,000 samples randomly from ViewRecDB-100K as the training set, we train ViewRecNet end-to-end using two RTX 5090 GPUs for 5 epochs. AdamW is used with a maximum learning rate of 1×10^{-5}, weight decay of 0.05, and a linear learning-rate schedule with a warmup ratio of 0.1. The batch size is 16 per GPU.

Baselines. We compare ViewRecNet with two 2D cropping methods, CACNet [5] and Venus-Q [3], and two 3D viewpoint recommendation methods, PPC [28] and SPAS [9]. For PPC, we use the last frame of its generated viewpoint-adjustment video as the recommended view. Since the training data and code for SPAS are unavailable, we reimplement it following the published method and train it on our ViewRecDB-100K.

Evaluation metrics. We evaluate all methods on ViewRecEval from three aspects.

(1) Pose-level consistency. Since most models only output images without camera poses, we treat DA3 [10] as a reliable pose estimator. The pose recovered from the generated image is used as the predicted viewpoint, while the pose recovered from the optimal image is used as the expert-selected viewpoint. Following [19, 10, 9], we report AUC@30 based on RRA, along with the average camera distance (Dist.) between the two viewpoints.

(2) Image-level consistency. Following [28], we use CLIP-I, PSNR, SSIM, and LPIPS as image-level metrics. Since our model outputs a recommended viewpoint rather than an image, we modify the data generation pipeline to generate the corresponding preview image.

(3) Preference-based evaluation. We conduct GPT-based and human preference evaluations using GPT-Pref, GPT-Imp, and Human-Pref.GPT-Pref is the percentage of pairwise comparisons in which GPT prefers the baseline result over the ViewRecNet result.=, while GPT-Imp measures whether the generated result is preferred over its suboptimal input. For Human-Pref, five raters evaluate all 1,000 test samples by jointly viewing the five results from four baselines and ViewRecNet and selecting the one with the best composition.

[2]– denotes not applicable, as our GPT rater is designed for viewpoint-changing image pairs and may be unreliable for crop-only comparisons.

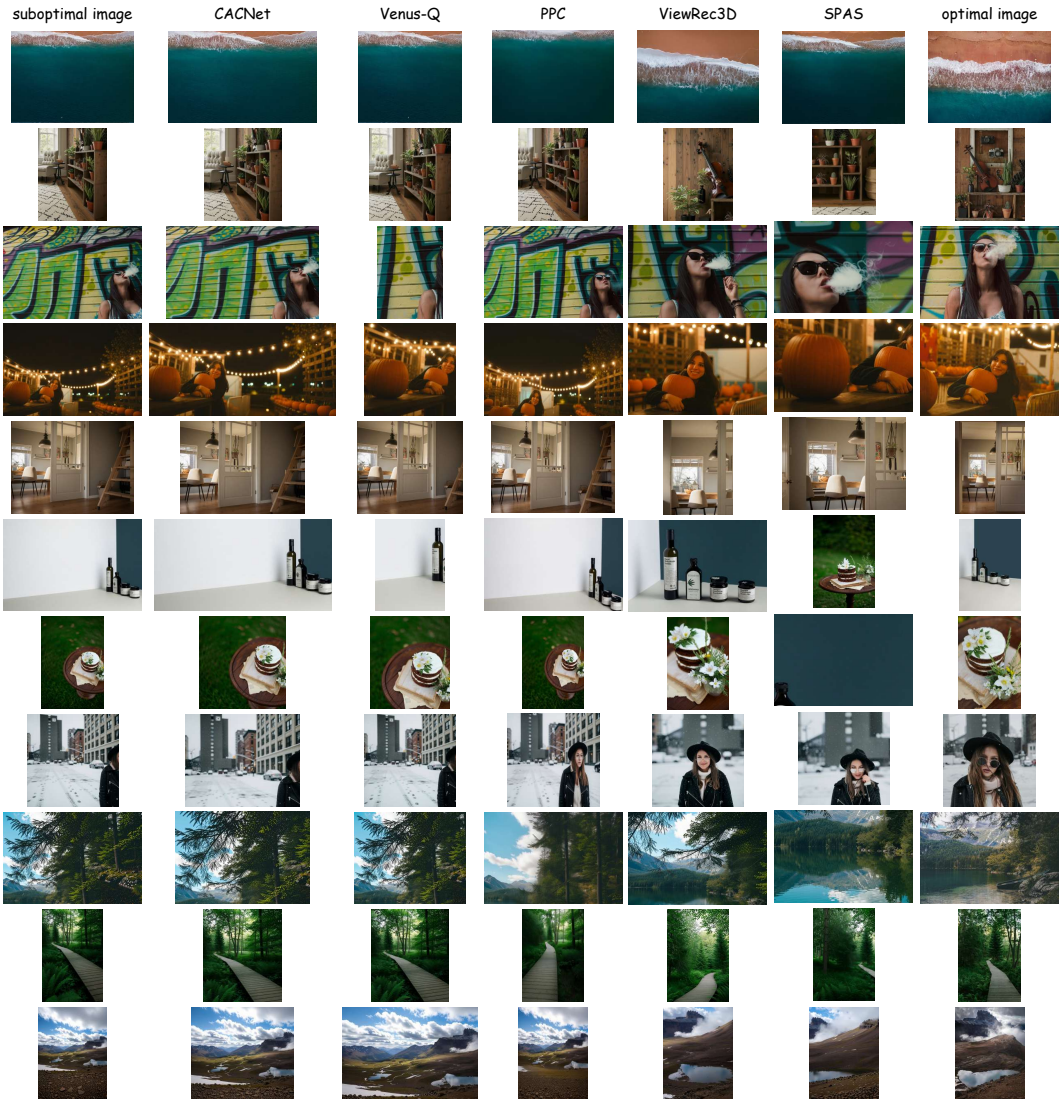
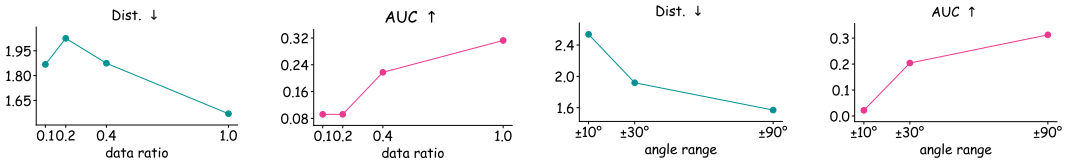


Figure 7: Qualitative comparison of 3D view recommendation results.

5.2 Main Results

Quantitative analysis. As shown in Table 2, ViewRecNet outperforms all baseline methods across pose-level consistency, image-level consistency, and preference-based evaluation, indicating that it can learn the patterns of expert-selected viewpoints from our ViewRecDB-100K dataset and recommend viewpoints that better align with human compositional preferences. Compared with 2D cropping methods, ViewRecNet performs better in preference-based evaluation, further suggesting that 2D cropping is constrained by the original viewpoint and has limited ability to handle compositional adjustments that require substantial changes in spatial relationships. Compared with existing 3D viewpoint recommendation methods, particularly SPAS trained on the same ViewRecDB-100K dataset, ViewRecNet still achieves better performance, indicating that our method can more effectively learn diverse viewpoint adjustments, including rotation, translation, and FoV changes, thereby enabling more sufficient and flexible 3D viewpoint recommendation.

Qualitative analysis. As shown in Fig. 7, ViewRecNet generally yields viewpoints with more coherent and visually pleasing compositions than the baseline methods. It can adjust tilted structural lines and visual guidance to make the composition more stable, clean, and visually comfortable. It can also coordinate the positions and relative proportions of different visual elements to form a more appropriate composition for the image content, for example by emphasizing the main subject



(a) (b) (c) (d)

Figure 8: Impact of different training data generation settings. (a, b) show the impact of training data scale, and (c, d) show the impact of the camera angle change range.

Table 3: Ablation on hierarchical filtering.

	AUC@30 ↑	Dist. ↓
w/o filtering	0.2166	1.7421
w/ filtering	**0.3126**	**1.5697**

Table 4: Ablation on ray-based supervision.

	AUC@30 ↑	Dist. ↓
w/o ray	0.2654	1.7351
w/ ray	**0.3126**	**1.5697**

or maintaining an overall balance among multiple elements. Compared with the two existing 3D baseline methods, ViewRecNet further demonstrates stronger viewpoint adjustment capability. Overall, ViewRecNet exhibits composition-aware capabilities in understanding scene structure and relationships among visual elements, representing a meaningful step toward AI photography.

5.3 Variant and Ablation Study

Impact of training data scale. We randomly select 10k, 20k, 40k, and compare them against the entire 100k training data. As shown in Fig. 8a and 8b, as the data increases, the performance of the trained model also increases (except for the average camera distance (Dist.) fluctuation between 10k and 20k data samples). This verifies the effectiveness of our large-scale dataset.

Impact of camera angle change range in training data. For viewpoint changes, we limit the pitch/yaw rotation ranges at three levels: $[-10, 10°]$, $[-30, 30°]$, and $[-90, 90°]$. Fig. 8c and 8d show that a broader range of camera pose changes in the training data helps the model learn more sufficient viewpoint adjustments, enabling it to better handle cases where the initial viewpoint differs substantially from the desired one. This further demonstrates the effectiveness of our data generation method.

Impact of hierarchical filtering. We evaluate the effect of hierarchical filtering on model performance in Tab. 3. Specifically, we combine the 97k samples rejected during the data generation process with ViewRecDB-100K to construct a mixed dataset, train ViewRecNet on this dataset, and compare it with the model trained only on ViewRecDB-100K. As shown in Tab. 3, after introducing these low-quality samples, model performance decreases noticeably despite the increase in training data scale. This suggests that, once the data scale is sufficiently large, data quality may be more important for viewpoint recommendation performance than simply increasing the amount of training data. Meanwhile, the results also show that our hierarchical filtering strategy is effective in identifying and removing low-quality samples.

Ray-based supervision. We construct a variant of ViewRecNet by removing the ray head and compare it with the full ViewRecNet to evaluate the effect of ray-based dense supervision. As shown in Tab. 4, removing the ray head leads to a performance drop, indicating that ray-based dense geometric supervision provides effective constraints during training and helps improve viewpoint recommendation performance.

5.4 Limitation and Broader Impact

ViewRecNet predicts only the recommended viewpoint, so image-level and preference-based evaluations rely on an additional preview generation pipeline involving 3D reconstruction, novel-view rendering, and image restoration. Errors introduced at these stages may affect the final preview and thus reduce evaluation accuracy. In addition, we use a single expert viewpoint as the optimal target, although photographic composition may admit multiple valid solutions. Modeling multiple plausible viewpoints and jointly predicting pose and image are important directions for future work.

Regarding broader societal impact, this work has the potential to lower the barrier to high-quality photography by serving as an AI photography assistant that recommends more suitable 3D viewpoints to users. The proposed ViewRecDB-100K dataset provides large-scale paired data between expert-selected viewpoints and their corresponding suboptimal viewpoints, while ViewRecNet offers a complementary modeling framework, together providing new data and methodological foundations for research on AI photographers.

6 Conclusion

In this paper, we presented ViewRecDB-100K, a viewpoint recommendation dataset constructed from expert-selected photos. To this end, we introduce a data generation method that renders high-quality image pairs from suboptimal viewpoints using 3D reconstruction. Moreover, a hierarchical filtering process based on a 3D expert model and an LLM is proposed for data quality control. On top of the dataset, we build a view recommendation network that uses ray-based dense geometric supervision. The proposed view recommendation model demonstrates strong results both quantitatively and qualitatively, and achieves the best result according to human user study, verifying the effectiveness of our data generation pipeline design.

7 Acknowledgment

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A Data Generation and Dataset Analysis

A.1 Data Generation and Filtering Details

Our data generation pipeline involves outpainting, single-image 3D reconstruction, novel view rendering, and image restoration. Each stage may introduce artifacts or geometric errors. We apply hierarchical filtering to remove unreliable samples at intermediate stages and after restoration. Below, we report stage-wise sample counts and examine changes in scene distributions associated with filtering.

Stage-wise filtering statistics. We use the first 212,000 photos from approximately 300,000 featured photos in Unsplash dataset [17] to construct ViewRecDB-100K. Figure A1 reports the number of images at each stage. During novel view generation, we randomly sample 200 candidate viewpoints per image and retain at most 10 rendered results that satisfy the basic constraints. Novel view filtering then retains at most two viewpoints per source photo, followed by restoration and final filtering. The resulting dataset contains 104,704 valid pairs from 76,010 source photos, corresponding to a source-photo yield of 35.85%. These statistics show that filtering excludes a substantial number of intermediate samples from the final dataset.

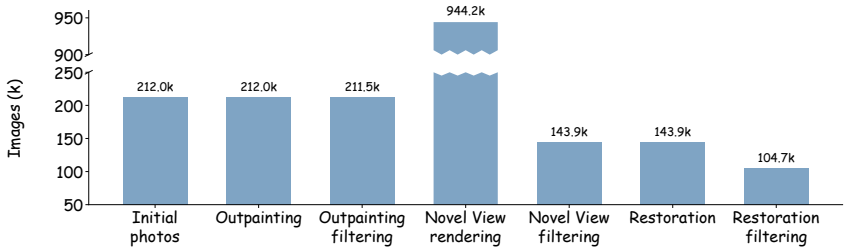


Figure A1: Stage-wise image counts in the data generation and filtering pipeline.

Scene distribution comparison. Figure A2 compares the scene distributions of all initial source photos and those contributing at least one valid pair after filtering. The proportions of nature and city scenes decrease slightly, while those of portraits, interiors, and still-life scenes increase slightly. All five categories still retain a sufficient number of samples, indicating that the hierarchical filtering process does not show an obvious bias toward removing or preserving any particular category. Therefore, the filtered dataset continues to cover diverse photographic scenarios while maintaining a reasonably balanced distribution across different scene types. These results further suggest that our hierarchical filtering strategy improves data quality without substantially reducing scene diversity, providing a reliable data foundation for subsequent model training and cross-scene generalization.

A.2 Viewpoint Distribution of ViewRecDB-100K

Figure A3 shows the yaw and pitch distributions in ViewRecDB-100K. Yaw changes span a broad range in both directions, whereas large pitch changes are relatively less frequent. Considering that substantial pitch adjustments are also uncommon in practical photography, this distribution is consistent with typical viewpoint changes in real-world shooting. In addition, since roll corresponds to an in-plane image rotation that can be easily handled by standard image processing operations, we do not explicitly model roll during data generation and set it to zero by default.

For translation, our representation is defined under a relative scale, so translation values across different scenes do not share a unified absolute physical scale. As a result, aggregating their global distribution is difficult to interpret in a physically meaningful way. We therefore focus primarily on the rotation distributions to characterize the range of viewpoint changes in the dataset, rather than further analyzing the global distribution of translation.

Overall, the angular distributions in ViewRecDB-100K cover the range of viewpoint adjustments commonly encountered in practical photography and retain sufficient variation across different directions. This indicates that the dataset provides diverse viewpoint changes and can reasonably simulate the typical viewpoint adjustment behavior of professional photographers.

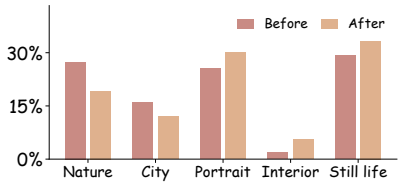


Figure A2: Scene distributions before and after hierarchical filtering.

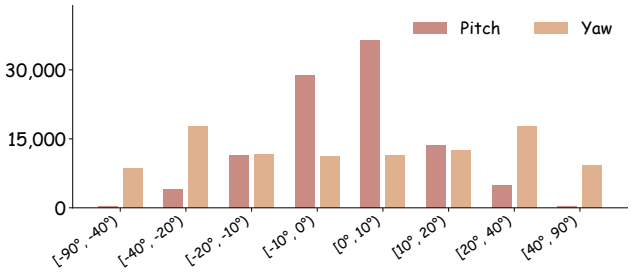


Figure A3: Rotation distributions on ViewRecDB-100K.

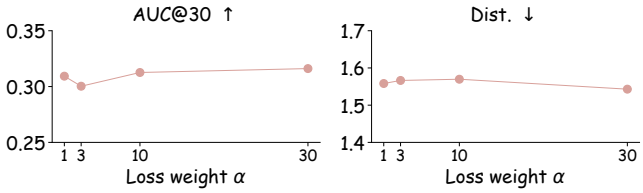


Figure B1: Sensitivity to the loss weight α.

Table B1: Comparison of different backbones.

Backbone	AUC@30↑	Dist.↓
DINOv2	0.2499	1.8417
CroCo	0.2092	2.0687
MuM	0.2524	1.9104
Frozen VGGT	0.0081	2.5081
VGGT (Ours)	**0.3126**	**1.5697**

B ViewRecNet Training and Model Analysis

B.1 Sensitivity to the Loss Weight

We investigate the sensitivity of ViewRecNet to the loss weight α, which balances the viewpoint loss against the orientation and ray reconstruction losses in the training objective. Figure B1 reports the results for $\alpha \in \{1, 3, 10, 30\}$.

Across the tested values, AUC@30 ranges from 0.3003 to 0.3161, while Dist. ranges from 1.5430 to 1.5697. These results suggest that ViewRecNet is not highly sensitive to α within the evaluated range. Although $\alpha = 30$ achieves the best results on both metrics, its improvement over the default setting is modest: 0.0035 in AUC@30 and 0.0267 in Dist. We retain $\alpha = 10$ as the default setting for consistency across experiments.

B.2 Impact of Different ViewRecNet Backbones

We further investigate the impact of the pretrained backbone on viewpoint recommendation. Specifically, we replace VGGT [18] with DINOv2 [15], CroCo [24], and MuM [14] while keeping the prediction heads and training settings unchanged. All backbones are fully fine-tuned during training. We additionally evaluate a frozen VGGT variant, where the backbone parameters are kept fixed and only the prediction heads are trained.

As shown in Table B1, the frozen VGGT variant performs substantially worse than the fully fine-tuned model, indicating that the capability of ViewRecNet does not simply come from directly inheriting the pretrained representations of VGGT. Instead, task-specific adaptation of the backbone is important for learning viewpoint recommendation. Meanwhile, different pretrained backbones exhibit clearly different performance after being trained under the same framework. Among them, VGGT achieves the best results on both metrics, suggesting that its pretrained geometric representations provide a stronger initialization for this task. These results show that ViewRecNet benefits from both task-specific training and the choice of geometric foundation model.

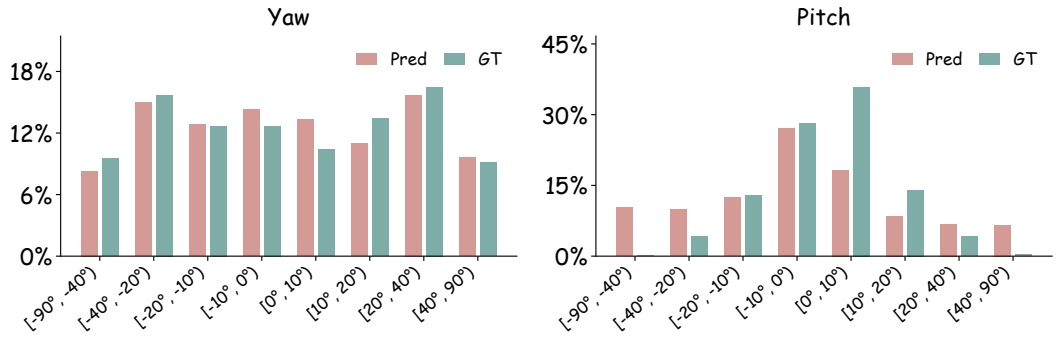


Figure C1: Distribution comparison of predicted (Pred) and ground-truth (GT) yaw and pitch on ViewRecEval.

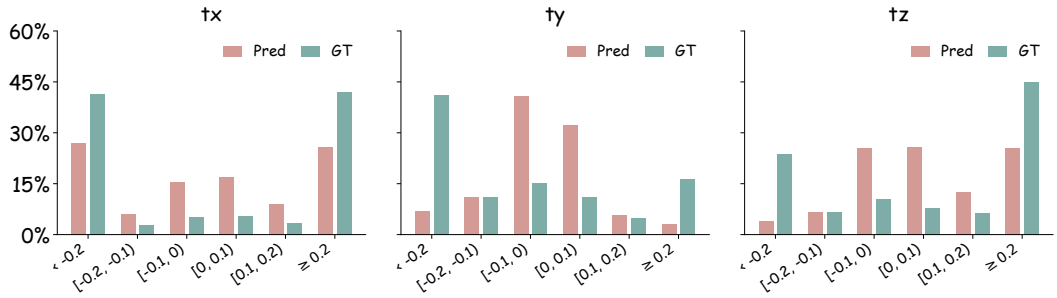


Figure C2: Distributions of predicted (Pred) and ground-truth (GT) translation components t_x, t_y, and t_z on ViewRecEval.

C Evaluation and Additional Results

C.1 Prediction Distribution Analysis

We further analysis the predicted and ground-truth viewpoints on ViewRecEval. Figure C1 and C2 compares the predicted and ground-truth yaw, pitch, and translation distributions on ViewRecEval. The predicted distributions retain substantial variation across different ranges and are not concentrated around zero or any fixed value, indicating that ViewRecNet does not collapse to a single fixed pose and instead produces diverse viewpoint adjustments according to the input.

C.2 Statistical Analysis of Human Preference

Table C1a reports Human-Pref with 95% confidence intervals, quantifying uncertainty in the estimated preference rates. Table C1b summarizes inter-rater agreement. The positive Fleiss' κ indicates agreement beyond chance, although participants do not consistently select the same result. This variation is consistent with the subjective nature of photographic composition, where multiple viewpoints may be visually appealing. Besides, the preference rates and agreement statistics provide complementary perspectives: the former summarize aggregate preferences across methods, while the latter characterize consistency among individual raters.

Table C1: Human preference analysis.

(a) Human preference with 95% CIs.

Method	Human-Pref. ↑	95% Confidence Interval
CACNet	20.50%	[18.76%, 22.28%]
Venus-Q	20.20%	[18.64%, 21.78%]
PPC	4.22%	[3.58%, 4.88%]
SPAS	10.60%	[8.98%, 12.26%]
ViewRecNet	**44.48%**	[42.42%, 46.60%]

(b) Inter-rater agreement.

Metric	Value
Observed agreement	0.5402
Expected agreement	0.2937
Fleiss' κ	0.3490

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